

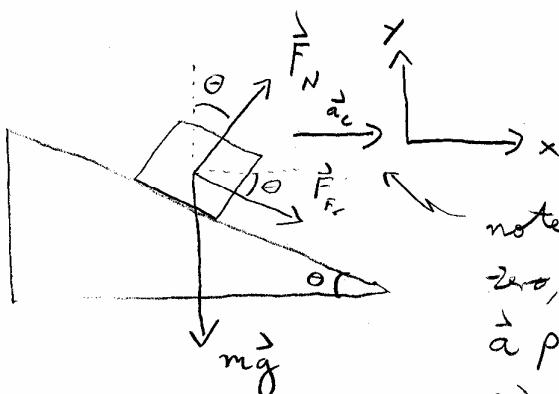
$$g = 9.8 \text{ m/s}^2$$

$$m = 1600 \text{ kg}$$

$$R = 420 \text{ m}$$

$$\theta = 5.4^\circ$$

$$v = 38 \text{ m/s}$$



note that the acceleration is not zero, as it moves on a circle \Rightarrow
 a points towards the center of the circle
 \Rightarrow centripetal acceleration!

There are three forces acting on the car and we know that the car is accelerating in the $+x$ -direction with an acceleration of magnitude $a_c = \frac{v^2}{r}$. We know that because the problem says that the car moves on a circular curve. Also we know that the car is not accelerating in the $+y$ -direction. Otherwise it would move up or down through the ground or in the air or down the incline!

This problem is 2-dimensional:

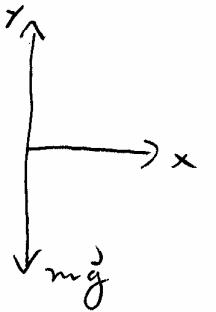
- choose coordinates: $+x$ is to the right (horizontal)
 $+y$ is up (vertical)
- use Newton and split it up in x and y

$$(\vec{F}_{\text{net}} = \sum \vec{F}) \rightarrow m\vec{g} + \vec{F}_f + \vec{F}_N = m\vec{a}$$

$\boxed{X:} (m\vec{g})_x + (\vec{F}_f)_x + (\vec{F}_N)_x = m(\vec{a})_x$

$\boxed{Y:} (m\vec{g})_y + (\vec{F}_f)_y + (\vec{F}_N)_y = m(\vec{a})_y$

components of $m\vec{g}$:



$$\Rightarrow (\vec{m}\vec{g})_x = 0$$

$$\text{and also } (\vec{m}\vec{g})_y = -mg$$

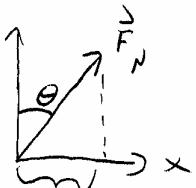
components of \vec{F}_f :



$$\Rightarrow (\vec{F}_f)_x = |\vec{F}_f| \cos \theta$$

$$\text{and also } (\vec{F}_f)_y = -|\vec{F}_f| \sin \theta$$

components of \vec{F}_N :



$$\Rightarrow (\vec{F}_N)_x = |\vec{F}_N| \sin \theta$$

$$\text{and also } (\vec{F}_N)_y = |\vec{F}_N| \cos \theta$$

components of \vec{a} :

The x-component of \vec{a} is $(\vec{a})_x = a_c = \frac{v^2}{R}$, as

the car moves in a horizontal circle. The y-component of \vec{a} is zero $(\vec{a})_y = 0$.

So I get:

$\boxed{X:} 0 + |\vec{F}_f| \cos \theta + |\vec{F}_N| \sin \theta = m \frac{v^2}{R} \quad (1.1)$

and similarly for Y (using $g = 9.8 \text{ m/s}^2$)

$\boxed{Y:} -mg - |\vec{F}_f| \sin \theta + |\vec{F}_N| \cos \theta = 0 \quad (1.2)$

a) $|\vec{F}_f| = ?$

- We do not know $|\vec{F}_N|$, but
- we have two equations. Use (1.2) to solve for $|\vec{F}_N|$, then plug that into (1.1) and solve for $|\vec{F}_f|$.

\Rightarrow Using the y -eqn.:

\boxed{y} :

$$|\vec{F}_N| \cos \theta = mg + |\vec{F}_f| \sin \theta$$

$$\Rightarrow |\vec{F}_N| = \frac{mg + |\vec{F}_f| \sin \theta}{\cos \theta}$$

plug this $|\vec{F}_N|$ into the x -eqn and I get

$$\boxed{x}: |\vec{F}_f| \cos \theta + \left(\frac{mg + |\vec{F}_f| \sin \theta}{\cos \theta} \right) \sin \theta = m \frac{v^2}{R}$$

$$\Rightarrow |\vec{F}_f| \cos \theta + mg \frac{\sin \theta}{\cos \theta} + |\vec{F}_f| \frac{\sin \theta}{\cos \theta} \sin \theta = m \frac{v^2}{R}$$

$$\Rightarrow |\vec{F}_f| \cos \theta + mg \tan \theta + |\vec{F}_f| \tan \theta \sin \theta = m \frac{v^2}{R}$$

$$\Rightarrow |\vec{F}_f| (\cos \theta + \tan \theta \sin \theta) + mg \tan \theta = m \frac{v^2}{R}$$

$$\Rightarrow |\vec{F}_f| (\cos \theta + \tan \theta \sin \theta) = m \frac{v^2}{R} - mg \tan \theta$$

$$\Rightarrow |\vec{F}_f| = \frac{m \frac{v^2}{R} - mg \tan \theta}{\cos \theta + \tan \theta \sin \theta}$$

$$|\vec{F}_{fr}| = \frac{m \frac{v^2}{R} - mg \tan \theta}{\cos \theta + \tan \theta \sin \theta}$$

using numbers:

$$|\vec{F}_{fr}| = \frac{1600 \text{ kg} \cdot \frac{38 \text{ m/s}^2}{420 \text{ m}} - 1600 \text{ kg} \cdot 9.8 \text{ m/s}^2 \tan 5.4^\circ}{\cos 5.4^\circ + \tan 5.4^\circ \sin 5.4^\circ}$$

$$\Rightarrow |\vec{F}_{fr}| = 4000.9 \text{ N}$$

6) What speed can you have if $|\vec{F}_{fr}| = 0$?

We have from a):

$$|\vec{F}_{fr}| = \frac{m \frac{v^2}{R} - mg \tan \theta}{\cos \theta + \tan \theta \sin \theta}$$

now $|\vec{F}_{fr}|$ is zero and we find v :

$$0 = \frac{m \frac{v^2}{R} - mg \tan \theta}{\cos \theta + \tan \theta \sin \theta}$$

$$\begin{aligned} 0 &= (\cos \theta + \tan \theta \sin \theta) \\ &\quad + mg \tan \theta \\ &\quad \div mg \end{aligned}$$

$$0 = \frac{mv^2}{R} - mg \tan \theta$$

$$\tan \theta = \frac{V^2}{g R}$$

$\cdot g R$

$$\Rightarrow \boxed{\sqrt{g R \tan \theta} = V}$$

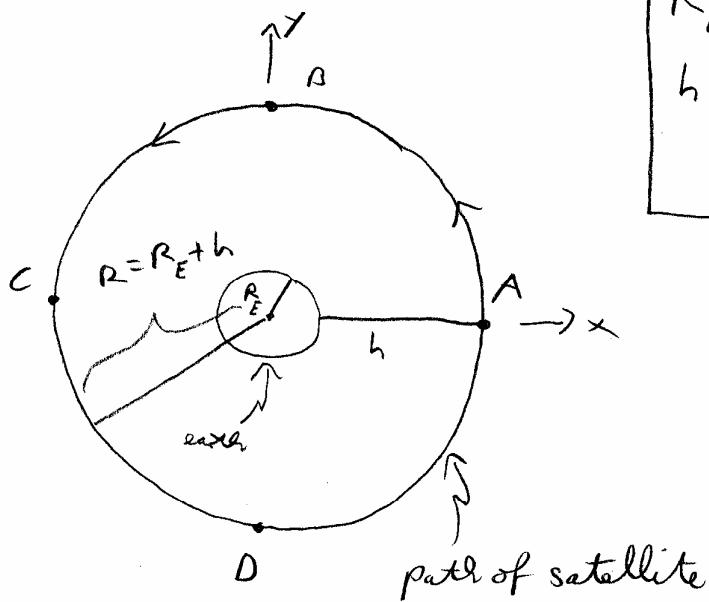
using numbers

$$V = \sqrt{9.8 \text{ m/s}^2 \cdot 420 \text{ m} \tan 5.4^\circ}$$

$$\Rightarrow \boxed{V = 19.7 \text{ m/s}}$$

(2)

uniform circular motion:



R_E : earth radius
 h : height of satellite

$$R_E = 6378 \text{ km}$$

$$h = 35878 \text{ km}$$

The satellite moves on a circle of radius

$$R = R_E + h = 6378 \text{ km} + 35878 \text{ km} = 42256 \text{ km}$$

a) What is its instantaneous velocity at point C?

The velocity is tangential to the circle, so it points down



or in the $-y$ -direction. $|\vec{v}|$ is constant as motion is uniform. It takes 1 day for it to go once round as it is in a geostationary orbit. So

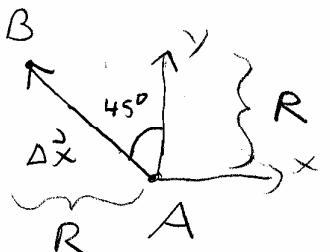
$$\Rightarrow |\vec{v}| = \frac{\text{distance}}{\text{time}} = \frac{\text{circumference}}{\text{day}} = \frac{2\pi R}{24 \text{ hrs}} = \frac{265502 \text{ km}}{86400 \text{ s}}$$

$$\Rightarrow |\vec{V}| = \frac{265502 \text{ m}}{86400 \text{ s}} = 3.07 \frac{\text{m}}{\text{s}}$$

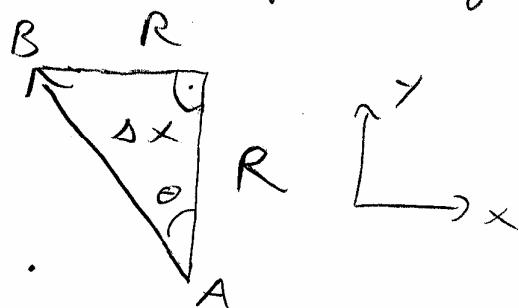
b) $\vec{V}_{\text{avg}} = \frac{\Delta \vec{x}}{\Delta t}$

where $\Delta \vec{x}$ is a vector pointing from A to B
and $\Delta t = \frac{1}{4} \text{ day}$

$\Delta \vec{x}$:



as A and B are rightmost and upmost points on the circle we have the following triangle



it is a right triangle and $\tan \Theta = \frac{R}{R} = 1$

$$\Rightarrow \Theta = \tan^{-1} 1 = 45^\circ \text{ this is } \Theta \text{ for } \Delta \vec{x} \text{ and is also } \Theta \text{ for } \vec{V}!$$

also $|\Delta \vec{x}| = \sqrt{R^2 + R^2} = \sqrt{2} R$

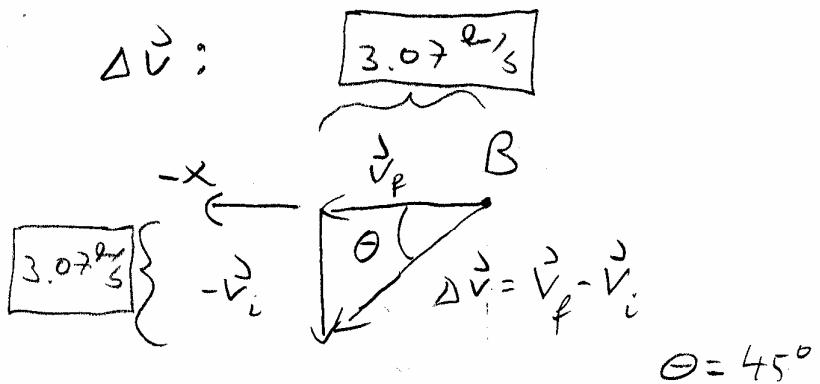
so $|\vec{V}_{\text{avg}}| = \frac{\sqrt{2} R}{\frac{1}{4} \text{ day}} = \frac{\sqrt{2} 42256 \text{ m}}{6 \text{ hrs}} = 2.77 \frac{\text{m}}{\text{s}}$

$$\text{c) } \vec{a}_{\text{avg}} = ?$$

$$\vec{a}_{\text{avg}} = \frac{\Delta \vec{v}}{\Delta t}$$

where $\Delta t = \frac{1}{4} \text{ day}$

$$\text{and } \Delta \vec{v} = \vec{v}_f - \vec{v}_i$$



from this picture, I get

$$\begin{aligned} |\Delta \vec{v}| &= \sqrt{(\Delta v_x)^2 + (\Delta v_y)^2} = \sqrt{\left[3.07 \frac{\text{km}}{\text{s}}\right]^2 + \left[-3.07 \frac{\text{km}}{\text{s}}\right]^2} \\ &= 4.34 \frac{\text{km}}{\text{s}} \end{aligned}$$

and from the picture

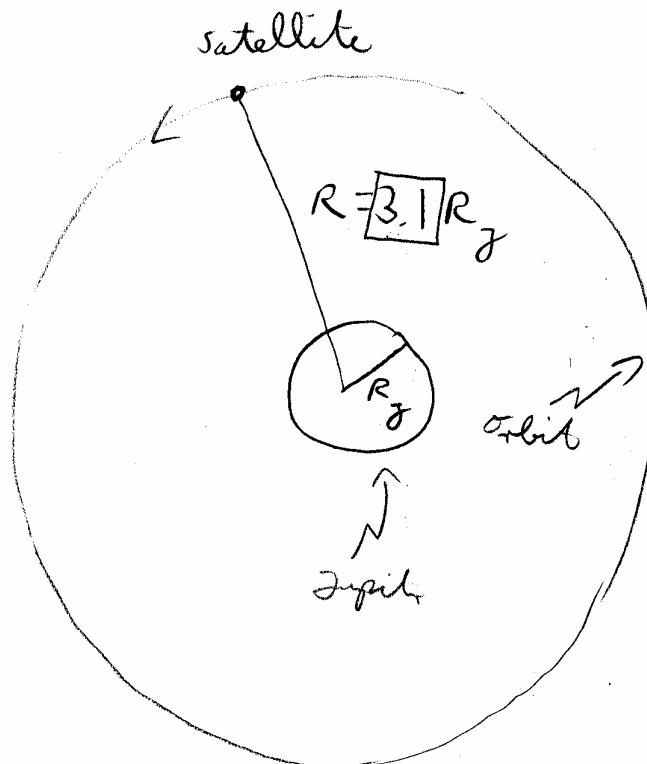
$\theta = 45^\circ$ with $-x$ -direction. This is angle of

$\Delta \vec{v}$ but is the same for \vec{a}_{avg}

then

$$|\vec{a}_{\text{avg}}| = \frac{4.34 \frac{\text{km}}{\text{s}}}{6 \text{ hrs}} = 2.07 \cdot 10^{-4} \frac{\text{km}}{\text{s}} = 0.201 \frac{\text{m}}{\text{s}}$$

(3)



$$R_J = 71505 \text{ km}$$

a at surface of
Jupiter = $a_0 = 25 \text{ N/kg}$

$$T = ?$$

We need to first find a at R , where the satellite is. We know a at the surface of Jupiter is $a_0 = 25 \text{ N/kg}$. We also know that the gravitational field decreases with distance as $\propto \frac{1}{R^2}$, so we know the ratio

$$\frac{a_0}{a} = \frac{\frac{1}{R_0^2}}{\frac{1}{R^2}} = \frac{R^2}{R_0^2} \quad \text{but } R_0 = R_J$$

the radius of Jupiter, so

$$\frac{a_0}{a} = \frac{R^2}{R_J^2} \Rightarrow a = a_0 \frac{R_J^2}{R^2}$$

But $R = \boxed{3.1} R_J$, so

$$a = a_0 \cdot \frac{\frac{1}{R_J^2} R_J^2}{\boxed{3.1}^2 R_J^2} = a_0 \cdot \frac{1}{\boxed{3.1}^2} = \frac{\boxed{25} \frac{N}{kg}}{\boxed{3.1}^2}$$

$$\Rightarrow a = \boxed{2.60} \frac{N}{kg}$$

The satellite is moving on a circle and nothing else, so

$$a = a_c = \frac{v^2}{R} \Rightarrow v = \sqrt{aR}$$

But also

$$\omega = \frac{v}{R} \text{ and } \omega = 2\pi f \text{ and } f = \frac{1}{T}$$

so

$$v = \frac{2\pi R}{T} \Rightarrow T = \frac{2\pi R}{v} \left(= \frac{\text{total distance}}{\text{time}} \right)$$

Plug in $v = \sqrt{aR}$ $\Rightarrow T = \frac{2\pi R}{\sqrt{aR}}$ and $R = \boxed{3.1} R_J$

So

$$T = \frac{2\pi \boxed{3.1} R_J}{\sqrt{2.6 \frac{N}{kg} \boxed{3.1} R_J}} = \frac{2\pi \boxed{3.1} \boxed{71505 \cdot 10^3 m}}{\sqrt{2.6 \frac{N}{kg} \boxed{3.1} \boxed{71505 \cdot 10^3 m}}}$$

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$$\text{so } \left(T = 58015.3 \text{ s} = 16.12 \text{ hrs} \right)$$

$$\textcircled{4} \quad v = \frac{2\pi R}{\Delta t}$$

for two satellites around the same planet, we have
from the gravitational field

$$\frac{a_1}{a_2} = \frac{R_2^2}{R_1^2}$$

$$\text{But also } a_1 = \frac{v_1^2}{R_1} \text{ and } a_2 = \frac{v_2^2}{R_2}$$

so also

$$\frac{v_1^2}{R_1} \cdot \frac{R_2}{v_2^2} = \frac{R_2^2}{R_1^2}$$

so

$$\boxed{v_2^2 = v_1^2 \frac{R_1}{R_2}} \Rightarrow v_2 = v_1 \sqrt{\frac{R_1}{R_2}}$$

$$\text{satellite 1: } v_1 = \frac{2\pi R_1}{\Delta t_1}$$

$$\boxed{R_1 = r} \\ \boxed{\Delta t_1 = 15 \text{ h}}$$

$$\text{satellite 2: } v_2 = \frac{2\pi R_2}{\Delta t_2}$$

$$\boxed{R_2 = 4.1 R_1} \\ \Delta t_2 = ?$$

$$\text{also from above } v_2 = v_1 \sqrt{\frac{R_1}{R_2}}$$

$$\text{so } \frac{2\pi R_2}{\Delta t_2} = v_1 \sqrt{\frac{R_1}{R_2}} = \frac{2\pi R_1}{\Delta t_1} \sqrt{\frac{R_1}{R_2}}$$

and thus

$$\frac{2\pi R_2}{\Delta t_2} = \frac{2\pi R_1}{\Delta t_1} \sqrt{\frac{R_1}{R_2}}$$

solve for Δt_2

$$\Delta t_2 = \Delta t_1 \frac{R_2}{R_1} \sqrt{\frac{R_2}{R_1}}$$

$$\boxed{\Delta t_2 = \Delta t_1 \left(\frac{R_2}{R_1} \right)^{3/2}}$$

with $\Delta t_1 = 15 \text{ h}$ and $R_2 = 4.1 R_1$

I get

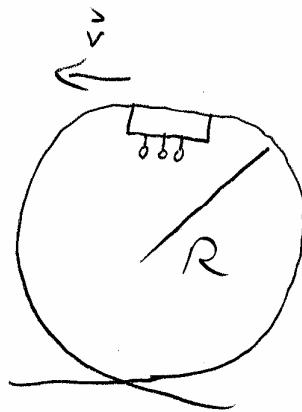
$$\Delta t_2 = \boxed{15 \text{ h}} \left(\boxed{4.1} \right)^{3/2}$$

$$\Delta t_2 = \boxed{15 \text{ h}} \cdot \boxed{8.3}$$

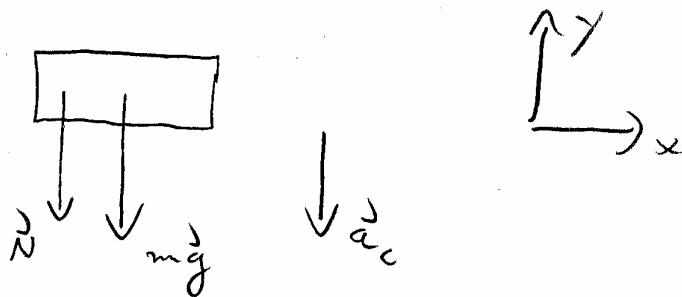
$$\Delta t_2 = \boxed{124.5 \text{ h}}$$



(5)



$$R = 24.4 \text{ m}$$



The normal force must be greater or equal zero so that the passengers are in contact with their seats. They just barely make it, when $N = 0$, so we newton

$$m\vec{g} + \vec{N} = m\vec{a}_c$$

and set $N = 0$ to find the minimum

$$m\vec{g} = m\vec{a}_c$$

\vec{a}_c and $m\vec{g}$ point downwards at the highest point, so only one equation (for y)

$\boxed{y:}$ $-mg = -m \frac{v^2}{R}$

solve for v :

$$v = \sqrt{g R}$$

$$v = \sqrt{9.8 \text{ m/s}^2 \cdot 24.4 \text{ m}}$$

$$v = 15.5 \text{ m/s}$$

⑥ fastest way to make U-turn at constant speed?

use $a = \frac{v^2}{R}$. What is the fastest way?

To find the fastest way, we need to find the time it takes. Constant speed, so

$$v = \frac{d}{\Delta t} \quad \begin{matrix} \leftarrow \text{distance} \\ d \end{matrix}$$

But $d = \frac{1}{2} 2\pi R$ as we go on a U-turn, we go half-way round a circle!

$$\text{so } v = \frac{\pi R}{\Delta t} \Rightarrow \Delta t = \frac{\pi R}{v}$$

$$\text{also } v = \sqrt{a R} \text{ so } \Delta t = \frac{\pi R}{\sqrt{a R}}$$

$$\Delta t = \frac{\pi R}{\sqrt{aR}} = \frac{\pi \sqrt{R} \sqrt{R}}{\sqrt{aR}} = \frac{\pi \sqrt{R}}{\sqrt{a}}$$

This is it, we have the total time in terms of radius and acceleration. To go faster we want

Δt to be smallest, so we immediately see that we want a small R and a large a !

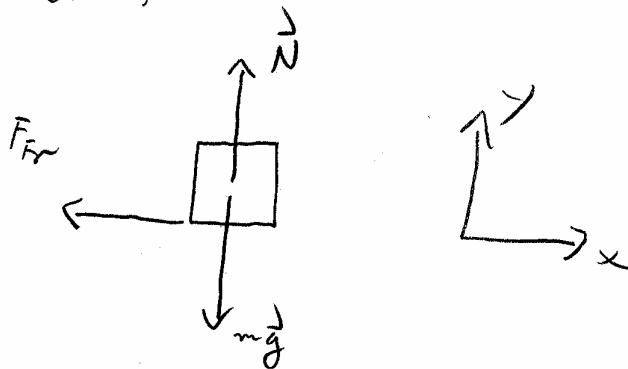
This can be seen from $\Delta t = \pi \sqrt{\frac{R}{a}}$, the smaller R and the larger a , the smaller Δt .

- a) From $\Delta t = \pi \sqrt{\frac{R}{a}}$ we want SIMMEST R
- b) Take SIMMEST R and LARGEST a from problem:

$$\Delta t_{min} = \pi \sqrt{\frac{5.1 \text{ m}}{3.1 \text{ m/s}^2}} = 4.03 \text{ s}$$



COIN on record:



It must move on a circle, so the force needed to keep this motion going is the static friction F_f with the ground. Nothing else can give the needed \vec{a}_c , as both normal force \vec{N} and gravity \vec{mg} are only vertical!

(But \vec{a}_c is horizontal of course as the record is not banked). The x -direction gives $N = mg$

$$\text{Note } f = \boxed{33.3 \text{ rpm}} = \frac{33.3}{\text{min}} \Rightarrow \boxed{V = 2\pi R f = 2\pi R \frac{33.3}{60 \text{ s}}}$$

$\sum (\vec{F})_x = m(\vec{a})_x$ circle



$F_{f_r \text{ MAX}}$

$$(\vec{F}_{F_r})_x = m(\vec{a})_x = -m a_c, \quad \boxed{F_{F_r} \text{ MAXXES OUT at } F_{F_r} = \mu_s N}$$

$$-\mu_s N = -m \frac{V^2}{R_{\text{MAX}}}$$

So

$$\mu_s N = m \frac{v^2}{R_{\max}}$$

replace $N = mg$ and $v = 2\pi R_{\max}$

$$\mu_s mg = m \frac{(2\pi)^2 R_{\max}^2 \left(\frac{33.3}{60s}\right)^2}{R_{\max}}$$

$$\mu_s mg = m \frac{(2\pi)^2 \left(\frac{33.3}{60s}\right)^2}{R_{\max}}$$

Solve for R_{\max}

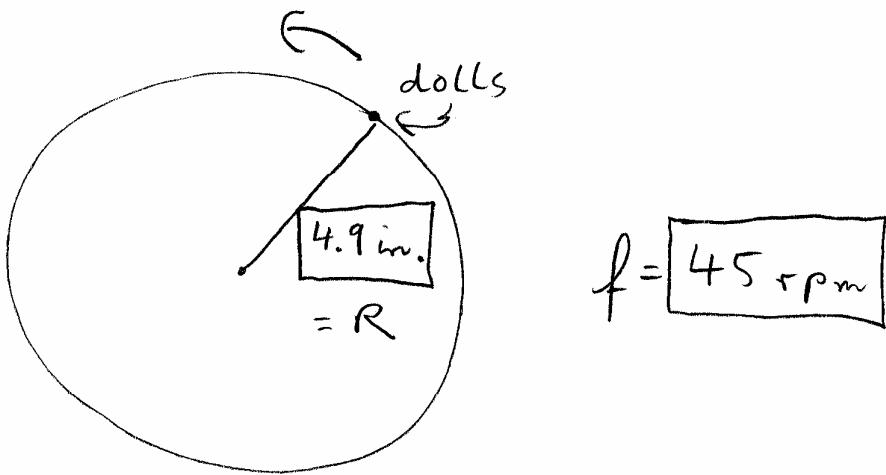
$$R_{\max} = \frac{\mu_s g}{(2\pi)^2 \left(\frac{33.3}{60s}\right)^2}$$

use $\mu_s = [0.1]$, $g = 9.8$ to get

$$R_{\max} = [0.0805 \text{ m}] = [8.05 \text{ cm}]$$

(8)

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a) $V = 2\pi R f = 2\pi [4.9 \text{ in.}] [45 \frac{1}{\text{min}}]$

But 1 inch = 2.54 cm = 0.0254 m

and 1 min = 60 s

so

$$V = 2\pi [4.9] \cdot 0.0254 \text{ m} \cdot \frac{45}{60 \text{ s}}$$

$$V = [0.587 \frac{\text{m}}{\text{s}}]$$

b) Same as problem 7:

in Y-direction:



in x-direction:



From $\times J$ get :

$$N = mg$$

$$\text{From } \gamma J \text{ get } |\vec{F}_r| = m|\vec{a}_c| = m \frac{v^2}{R} = m\omega^2 R$$

$$\text{where this time } J \text{ used } \frac{v^2}{R} = \frac{\omega^2 R^2}{R} = \omega^2 R$$

and, as $\omega = 2\pi f$, I get

$$\text{For } \gamma \text{ direction } |\vec{F}_r| = m(2\pi f)^2 R \quad \text{r.p.m.no.}$$

$$\text{but } f \text{ is given, for me it is } f = \frac{45}{\text{min}} = \frac{45}{60\text{s}}$$

so the friction is in magnitude

$$\begin{aligned} |\vec{F}_r| &= m \left(2\pi \frac{45}{60\text{s}}\right)^2 [4.9] \text{ in.} \\ &= m \left(2\pi \frac{45}{60\text{s}}\right)^2 [4.9] \cdot 0.0254 \text{ m} \end{aligned}$$

$$\text{But } |\vec{F}_r| \leq \mu_s mg = [0.14] mg$$

So the question is if

$$\underbrace{[0.14] \cdot 9.8 \text{ m/s}^2}_{\text{MAX FRICTION}} \stackrel{(2)}{\geq} \underbrace{\left(2\pi \frac{45}{60\text{s}}\right)^2 [4.9] \cdot 0.0254 \text{ m}}_{\text{rhs}}$$

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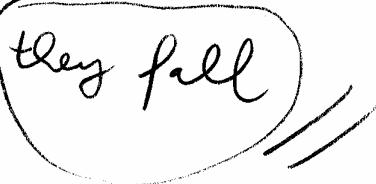
evaluating both sides:

$$\boxed{1.32} \frac{m}{s^2} \stackrel{(2)}{\geq} \boxed{2.76} \frac{m}{s^2}$$

The MAX FRICTION is $\boxed{1.32} \frac{m}{s^2} \cdot \text{mass}$

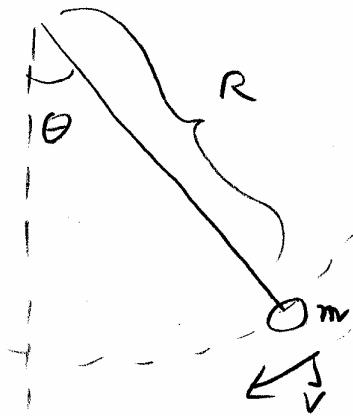
force needed to keep them on their circle at $\boxed{45}$ r.p.m.

is $\boxed{2.76} \frac{m}{s^2} \cdot \text{mass} \Rightarrow$ FRICTION not strong

enough \Rightarrow  they fall

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(9)



$$\theta = 15.0^\circ$$

$$g = 9.8 \text{ m/s}^2$$

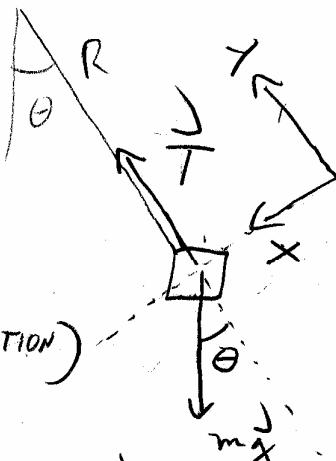
$$m = 1 \text{ kg}$$

$$R = 0.8 \text{ m}$$

$$v = 1.4 \text{ m/s}$$

Do FBD

(ONLY GRAVITY AND
TENSION BUT ALSO
NONZERO ACCELERATION)



$$\sum \vec{F} = m\vec{a} \Rightarrow \vec{T} + \vec{mg} = m\vec{a}$$

$$x(\text{tangent}): +mg \sin \theta + 0 = m a_t$$

$$y(\text{centrip}): T - mg \cos \theta = m a_c$$

$$\text{From } x: a_t = +g \sin \theta$$

$$a_t = 9.8 \text{ m/s}^2 \sin[15.0^\circ] = 2.54 \text{ m/s}^2$$

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From 7: $T = ma_c + mg \cos \theta$

$$\text{But } a_c = \frac{v^2}{R} = \frac{1.4 \text{ (m/s)}^2}{0.8 \text{ m}} = 2.45 \text{ m/s}^2$$

and with this

$$T = m [2.45] \text{ m/s}^2 + mg \cos \theta$$

$$= [1 \text{ kg}] \cdot \underbrace{[2.45] \text{ m/s}^2}_{=a_c} + [1 \text{ kg}] \cdot [1.8 \text{ m/s}^2 \cos 15.0^\circ]$$

$$T = 11.9 \text{ N}$$