

## Vector calculus (Differentiation)

① Variation in 1-D

$$f = f(x) \quad df = dx \frac{d}{dx} f$$

② Variation in 3-D

$$f = f(x, y, z) \quad df = dx \frac{\partial}{\partial x} f + dy \frac{\partial}{\partial y} f + dz \frac{\partial}{\partial z} f$$

③ Partial derivative - illustrative example

$$f(x, y, z) = x^3 y^2 + x \sin y + z$$

$$\frac{\partial}{\partial x} f = 3x^2 y^2 + \sin y$$

$$\frac{\partial}{\partial y} f = 2x^3 y + x \cos y$$

$$\frac{\partial}{\partial z} f = 1$$

④ We can write

$$df = dx \frac{\partial}{\partial x} f + dy \frac{\partial}{\partial y} f + dz \frac{\partial}{\partial z} f \\ = d\vec{l} \cdot \vec{\nabla} f$$

where

$$d\vec{l} = dx \hat{x} + dy \hat{y} + dz \hat{z}$$

$$\vec{\nabla} = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$$

⑤ Example :

$$\begin{aligned}
 (i) \quad \vec{\nabla} \delta &= \vec{\nabla} \sqrt{x^2 + y^2 + z^2} \\
 &= \hat{x} \frac{\partial}{\partial x} \sqrt{x^2 + y^2 + z^2} + \hat{y} \frac{\partial}{\partial y} \sqrt{x^2 + y^2 + z^2} + \hat{z} \frac{\partial}{\partial z} \sqrt{x^2 + y^2 + z^2} \\
 &= \frac{x \hat{x} + y \hat{y} + z \hat{z}}{\delta} \\
 &= \frac{\vec{\delta}}{\delta} = \hat{\delta}
 \end{aligned}$$

$$\delta = \sqrt{x^2 + y^2 + z^2}$$

$$\vec{\delta} = x \hat{x} + y \hat{y} + z \hat{z}$$

$$\begin{aligned}
 (ii) \quad \vec{\nabla} \delta^n &= n \delta^{n-1} \vec{\nabla} \delta \\
 &= n \delta^{n-1} \hat{\delta}
 \end{aligned}$$

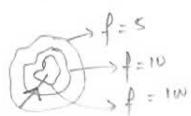
Griffiths defines.

$$\vec{H} = \vec{\delta} - \vec{\delta}'$$

$$(iii) \quad \vec{\nabla} |\vec{\delta} - \vec{\delta}'|^n = n |\vec{\delta} - \vec{\delta}'|^{n-1} \frac{(\vec{\delta} - \vec{\delta}')}{|\vec{\delta} - \vec{\delta}'|}$$

⑥ Interpretation :

(i)  $\vec{\nabla} f$  is normal to the curve/surface,  $f = \text{constant}$ , in 2-D / 3-D.



(ii)  $\vec{\nabla} f$  points in the direction of maximum change in  $f$ , and  $\alpha$  is the slope at the point.

$\rightarrow x^2 + y^2 + z^2 = \delta^2$  describes surface of a sphere, and  $\vec{\nabla} (x^2 + y^2 + z^2) = 2\vec{\delta}$  is normal to this surface.

$\rightarrow x^2 + y^2 - z^2 \tan^2 \theta = 0$  describes a surface of cone, constant  $\theta$ ,

$\vec{\nabla} (x^2 + y^2 - z^2 \tan^2 \theta) = 2x \hat{x} + 2y \hat{y} - 2z \tan^2 \hat{z}$  points in the direction of  $\hat{\theta}$ , normal to the cone.

⑦ Example (Griffiths 4e, problem 1.12)

Height of a hill is given by

$$h(x, y) = 10 [2xy - 3x^2 - 4y^2 - 18x + 28y + 12]$$

(i) where is top of hill located?

$$\vec{\nabla} h = 10(2y - 6x - 18)\hat{i} + 10(2x - 8y + 28)\hat{j}$$

$$\vec{\nabla} h = 0 \Rightarrow x = -2, y = 3 \quad \leftarrow \text{location of top}$$

(ii) how high is the hill?

$$h(-2, 3) = 720 \text{ miles.}$$

⑧ Divergence of a vector field.

$$\vec{\nabla} \cdot \vec{A} = \left[ \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right] \cdot \left[ \hat{i} A_x + \hat{j} A_y + \hat{k} A_z \right]$$

$$= \frac{\partial}{\partial x} A_x + \frac{\partial}{\partial y} A_y + \frac{\partial}{\partial z} A_z$$

interpretation — sum of magnitudes of three derivatives  
 — a measure of divergence of the field  $\vec{A}$ ,   
 source and sink of a field.

⑨ Curl of a vector field.

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \hat{i} \left( \frac{\partial}{\partial y} A_z - \frac{\partial}{\partial z} A_y \right) - \hat{j} \left( \frac{\partial}{\partial x} A_z - \frac{\partial}{\partial z} A_x \right) + \hat{k} \left( \frac{\partial}{\partial x} A_y - \frac{\partial}{\partial y} A_x \right)$$

interpretation — a measure of vorticity of the field,  
 example how much the water is spinning  
 inside a sink.

(10) Example

$$\begin{aligned}
 \vec{\nabla} \cdot \vec{\delta} &= \nabla^i x^j \\
 &= \frac{\partial}{\partial x^i} x^j \\
 &= \delta_{ij} \\
 &= \uparrow \downarrow
 \end{aligned}
 \Rightarrow \quad \vec{\nabla} \times \vec{\delta} = e^{ijk} \delta_{jk} = e^{iij} = 0$$

$$\vec{\nabla} \cdot \vec{\delta} = \delta_{ii} = 3$$

(11) Example

$$\begin{aligned}
 (i) \quad \vec{\nabla} \cdot \vec{\frac{\delta}{x}} &= (\vec{\nabla} \cdot \vec{\delta}) \frac{1}{x} + \vec{\delta} \cdot \vec{\nabla} \frac{1}{x} \\
 &= \uparrow \frac{1}{x} - \vec{\delta} \frac{1}{x^2} \vec{\nabla} x \\
 &= \uparrow \frac{1}{x} - \frac{\vec{\delta} \vec{x}}{x^3}
 \end{aligned}
 \Rightarrow \quad \vec{\nabla} \cdot \vec{\frac{\delta}{x}} = \frac{3}{x} - \frac{1}{x} = \frac{2}{x}$$

$$\vec{\nabla} \times \vec{\frac{\delta}{x}} = 0$$

$$\begin{aligned}
 (ii) \quad \vec{\nabla} \cdot \vec{\frac{\delta}{x^2}} &= (\vec{\nabla} \cdot \vec{\delta}) \frac{1}{x^2} + \vec{\delta} \cdot \vec{\nabla} \frac{1}{x^2} \\
 &= \uparrow \frac{1}{x^2} - 2 \frac{\vec{\delta}}{x^3} \vec{\nabla} x \\
 &= \uparrow \frac{1}{x^2} - 2 \frac{\vec{\delta} \vec{x}}{x^4}
 \end{aligned}
 \Rightarrow \quad \vec{\nabla} \cdot \vec{\frac{\delta}{x^2}} = \frac{3}{x^2} - \frac{2}{x^2} = \frac{1}{x^2}$$

$$\vec{\nabla} \times \vec{\frac{\delta}{x^2}} = 0$$

$$\begin{aligned}
 (iii) \quad \vec{\nabla} \cdot \vec{\frac{\delta}{x^3}} &= \uparrow \frac{1}{x^3} - 3 \frac{\vec{\delta} \vec{x}}{x^5} \\
 &?
 \end{aligned}
 \Rightarrow \quad \vec{\nabla} \cdot \vec{\frac{\delta}{x^3}} = ?$$

$$\vec{\nabla} \times \vec{\frac{\delta}{x^3}} = 0$$

## (12) Laplacian

$$\vec{\nabla} \cdot \vec{\nabla} f = \vec{\nabla}^2 f \\ = \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) f$$

(13)  $\vec{\nabla} \times \vec{\nabla} f = 0$

$$\begin{aligned} \vec{\nabla} \times \vec{\nabla} f &= \epsilon_{ijk} \nabla^i \nabla^k \\ &= \frac{1}{2} [ \epsilon_{ijk} \nabla^i \nabla^k + \epsilon_{ijk} \nabla^k \nabla^i ] \\ &= \frac{1}{2} [ \epsilon_{ijk} \nabla^i \nabla^k + \epsilon_{ikj} \nabla^k \nabla^i ] \\ &= \frac{1}{2} [ \epsilon_{ijk} \nabla^i \nabla^k + \epsilon_{ikj} \nabla^i \nabla^k ] \\ &= \frac{1}{2} ( \epsilon_{ijk} + \epsilon_{ikj} ) \nabla^i \nabla^k \\ &= \frac{1}{2} ( \epsilon_{ijk} - \epsilon_{ikj} ) \nabla^i \nabla^k \\ &= 0 \end{aligned}$$

$\nabla^i \nabla^k$  - symmetric in  $jk$   
 $\epsilon_{ijk}$  - antisymmetric

(trick on dummy indices)

( $\because \nabla^k \nabla^i = \nabla^i \nabla^k$ )

(14)  $(\vec{\nabla} f) \times (\vec{\nabla} g) = \epsilon_{ijk} (\nabla^i f) (\nabla^k g)$

note that  $(\nabla^i f) (\nabla^k g) \neq (\nabla^k f) (\nabla^i g)$   
 and thus is not symmetric in  $j \leftrightarrow k$ .

(15)  $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = \epsilon_{ijk} \nabla^i \nabla^j A^k$   
 $= 0$  (due to conflict between symmetry and antisymmetry.)

(16) Remember:

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$$

$$\begin{aligned}
 (17) \quad \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) &= \epsilon_{ijk} \nabla^j (\epsilon^{kmn} \nabla^m A^n) \\
 &= \epsilon_{kij} \epsilon^{kmn} \nabla^i \nabla^m A^n \\
 &= (\delta^{im} \delta^{jn} - \delta^{in} \delta^{jm}) \nabla^i \nabla^m A^n \\
 &= \nabla^j \nabla^i A^j - \nabla^i \nabla^j A^i \\
 &= \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}
 \end{aligned}$$

$$\begin{aligned}
 (18) \quad \vec{A} \times (\vec{\nabla} \times \vec{B}) &= \epsilon_{ijk} A^i \epsilon^{kmn} \nabla^m B^n \\
 &= (\delta^{im} \delta^{jn} - \delta^{in} \delta^{jm}) A^i \nabla^m B^n \\
 &= A^j \nabla^i B^j - A^i \nabla^j B^i \\
 &= (\vec{\nabla} \cdot \vec{B}) \cdot \vec{A} - \vec{A} \cdot \vec{\nabla} \vec{B}
 \end{aligned}$$

$$\begin{aligned}
 (19) \quad \vec{\nabla} \times (\vec{A} \times \vec{B}) &= \epsilon_{ijk} \nabla^i \epsilon^{kmn} A^m B^n \\
 &= (\delta^{im} \delta^{jn} - \delta^{in} \delta^{jm}) \nabla^i (A^m B^n) \\
 &= (\delta^{im} \delta^{jn} - \delta^{in} \delta^{jm}) [(\nabla^i A^m) B^n + A^m (\nabla^i B^n)] \\
 &= (\nabla^j A^i) B^j + A^i \nabla^j B^j - (\nabla^i A^j) B^i - A^j (\nabla^i B^i) \\
 &= (\vec{B} \cdot \vec{\nabla}) \vec{A} + \vec{A} (\vec{\nabla} \cdot \vec{B}) - (\vec{\nabla} \cdot \vec{A}) \vec{B} - (\vec{A} \cdot \vec{\nabla}) \vec{B}
 \end{aligned}$$