

Date: 2014 Aug 18

①

Maxwell's equations

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0} \quad Q = \int d^3r \rho$$

$$\oint \vec{B} \cdot d\vec{a} = 0$$

$$\oint d\vec{l} \cdot \vec{E} = -\frac{\partial}{\partial t} \Phi_B$$
$$\Phi_B = \int_{\text{surface}} \vec{B} \cdot d\vec{a}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \mu_0 \vec{J}$$

$$\oint d\vec{l} \cdot \vec{B} = \mu_0 \epsilon_0 \frac{\partial}{\partial t} \Phi_E + \mu_0 I$$

$$\Phi_E = \int_{\text{surface}} \vec{E} \cdot d\vec{a}$$

$$I = \int_{\text{surface}} \vec{J} \cdot d\vec{a}$$

$$\vec{D} = \epsilon_0 \vec{E}$$

$$\vec{B} = \mu_0 \vec{H}$$

②

Photons are a particular manifestation of electric and magnetic fields.

① Vectors

$$\vec{A} = A_1 \hat{e}_1 + A_2 \hat{e}_2 + A_3 \hat{e}_3$$

Let $\hat{e}_1 = \hat{x}$
 $\hat{e}_2 = \hat{y}$
 $\hat{e}_3 = \hat{z}$

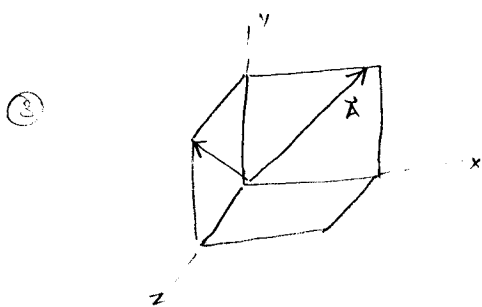
$$A_i \equiv (A_1, A_2, A_3)$$

→ an array of numbers.
 → components of a vector,
 tensor of rank 1.

② $\vec{C} = \vec{A} \pm \vec{B}$

$$\vec{A} \cdot \vec{B}$$

$$\vec{A} \times \vec{B}$$



$$\vec{A} = (1, 1, 0) \quad |\vec{A}| = \sqrt{2}$$

$$\vec{B} = (0, 1, 1) \quad |\vec{B}| = \sqrt{2}$$

$$\vec{A} \cdot \vec{B} = 1 = AB \cos \theta$$

$$1 = 2 \cos \theta$$

$$\theta = \cos^{-1}\left(\frac{1}{2}\right) = 60^\circ$$

④ Linear transform of a vector

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$x' = \cos \theta x + \sin \theta y$$

$$y' = -\sin \theta x + \cos \theta y$$

$$\begin{aligned} x'^2 + y'^2 &= (\cos \theta x + \sin \theta y)^2 + (-\sin \theta x + \cos \theta y)^2 \\ &= x^2 \underbrace{(\cos^2 \theta + \sin^2 \theta)}_{=1} + y^2 \underbrace{(\sin^2 \theta + \cos^2 \theta)}_{=1} \\ &\quad + 2xy \sin \theta \cos \theta - 2xy \sin \theta \cos \theta \\ &= x^2 + y^2 \end{aligned}$$

⑤

$$x'_i = R_{ij} x_j = \sum_{j=1}^2 R_{ij} x_j$$

← summation convention,
differs free index will
dummy index

$$\begin{aligned} \underline{i=1} \quad x'_1 &= R_{1j} x_j \\ &= R_{11} x_1 + R_{12} x_2 \end{aligned}$$

$$\begin{aligned} \underline{i=2} \quad x'_2 &= R_{2j} x_j \\ &= R_{21} x_1 + R_{22} x_2 \end{aligned}$$

$$R_{ij} \equiv \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

⑥

$$\begin{aligned}
 \vec{x}' \cdot \vec{x}' &= x'_1 x'_1 + x'_2 x'_2 \\
 &= x'_i x'_i \\
 &= (R_{ij} x_j) (R_{ik} x_k) \\
 &= R_{ij} R_{ik} x_j x_k.
 \end{aligned}$$

⑦

$$\begin{aligned}
 \vec{x} \cdot \vec{x} &= x_1 x_1 + x_2 x_2 \\
 &= x_j x_j \\
 &= x_j \delta_{jk} x_k.
 \end{aligned}$$

⑧ Kronecker delta

$$\delta_{ij} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

⑨

$$\begin{aligned}
 \vec{x}' \cdot \vec{x}' &= \vec{x} \cdot \vec{x} && (\text{definition of a vector}) \\
 \Rightarrow R_{ij} R_{ik} &= \delta_{jk}.
 \end{aligned}$$

$$\textcircled{10} \quad \overleftrightarrow{R} = R_{ij} = \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix}$$

$$\overleftrightarrow{R}^T = R_{ji} = \begin{pmatrix} R_{11} & R_{21} \\ R_{12} & R_{22} \end{pmatrix}$$

$$\begin{aligned} \textcircled{11} \quad \overleftrightarrow{C} &= \overleftrightarrow{M} \cdot \overleftrightarrow{N} = M_{ji} N_{ik} \\ &= \begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix} \begin{pmatrix} N_{11} & N_{12} \\ N_{21} & N_{22} \end{pmatrix} \\ &= \begin{pmatrix} M_{11} N_{11} + M_{12} N_{21} & M_{11} N_{12} + M_{12} N_{22} \\ M_{21} N_{11} + M_{22} N_{21} & \end{pmatrix} \\ &= \begin{pmatrix} M_{1i} N_{i1} & M_{1i} N_{i2} \\ M_{2i} N_{i1} & M_{2i} N_{i2} \end{pmatrix} \end{aligned}$$

$$\overleftrightarrow{C} = \overleftrightarrow{M} \cdot \overleftrightarrow{N}$$

$$C_{jk} = M_{ji} N_{ik}$$

(12)

$$R_{ij} R_{ik} = \delta_{jk}$$

$$(R^T)_{ji} R_{ik} = \delta_{jk}$$

$$\vec{R}^T \cdot \vec{R} = \vec{1}$$

(13)

Rotation in arbitrary dimension.

$$x'_i = R_{ij} x_j$$

$$R_{ij} R_{ik} = \delta_{jk}$$

(14)

Vector
tensor

$$A'_i = R_{ij} A_j$$

$$B'_{ij} = R_{im} R_{jn} B_{mn}$$

(15)

$$\delta_{ij} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

$$\epsilon_{ijk} = \begin{cases} +1 & \text{if } i=1, j=2, k=3 \\ -1 & \text{if } i=1, j=3, k=2 \\ 0 & \text{otherwise} \end{cases}$$

and even permutations
and even "

(16)

$$\begin{aligned}\vec{A} \cdot \vec{B} &= A_i B_i \\ &= A_i \delta_{ij} B_j\end{aligned}$$

(17)

$$\begin{aligned}\vec{C} &= \vec{A} \times \vec{B} \\ &= (A_2 B_3 - A_3 B_2) \hat{x} + (A_3 B_1 - A_1 B_3) \hat{y} + (A_1 B_2 - A_2 B_1) \hat{z}\end{aligned}$$

$$C_1 = A_2 B_3 - A_3 B_2$$

$$C_2 = A_3 B_1 - A_1 B_3$$

$$C_3 = A_1 B_2 - A_2 B_1$$

$$\epsilon_{ijk} A_j B_k = ?$$

$$\begin{aligned}i=1 \quad \epsilon_{ijk} A_j B_k &= \epsilon_{11k} A_1 B_k + \epsilon_{12k} A_2 B_k + \epsilon_{13k} A_3 B_k \\ &= \cancel{\epsilon_{11k} A_1 B_k} + \epsilon_{12k} A_2 B_k + \epsilon_{13k} A_3 B_k \\ &= \epsilon_{123} A_2 B_3 + \epsilon_{132} A_3 B_2 \\ &= A_2 B_3 - A_3 B_2\end{aligned}$$