

① Variation

$$f(x+\delta x) = f(x) + \delta x \frac{df}{dx} + \frac{1}{2} \delta x^2 \frac{d^2f}{dx^2} + \dots$$

$$= f(x) + \delta x \frac{df}{dx} \quad (\text{upto leading order})$$

$$\delta f = \delta x \frac{df}{dx}$$

$$\delta f = f(x+\delta x) - f(x)$$

②

$$f(x+\delta x, y+\delta y) = f(x, y+\delta y) + \delta x \frac{\partial}{\partial x} f(x, y+\delta y)$$

$$= f(x, y) + \delta y \frac{\partial}{\partial y} f(x, y) + \delta x \frac{\partial}{\partial x} \left[f(x, y) + \delta y \frac{\partial}{\partial y} f(x, y) \right]$$

$$= f(x, y) + \delta x \frac{\partial}{\partial x} f + \delta y \frac{\partial}{\partial y} f \quad (\text{upto leading order})$$

$$\delta f = \delta x \frac{\partial}{\partial x} f + \delta y \frac{\partial}{\partial y} f$$

$$\delta f = f(x+\delta x, y+\delta y) - f(x, y)$$

③ In 3-D

$$\delta f = \delta x \frac{\partial}{\partial x} f + \delta y \frac{\partial}{\partial y} f + \delta z \frac{\partial}{\partial z} f$$

④ Partial derivative - illustrative example.

$$f(x, y, z) = x^3 y^2 + x \sin y + z^5$$

$$\frac{\partial f}{\partial x} = 3x^2 y^2 + \sin y$$

$$\frac{\partial f}{\partial y} = 2x^3 y + x \cos y$$

$$\frac{\partial f}{\partial z} = 5z^4$$

⑤ Total derivative and partial derivative

$$L = L(x(t), t)$$

$$\frac{dL}{dt} = \frac{\partial L}{\partial t} + \frac{dx}{dt} \frac{\partial L}{\partial x}$$

In the absence of internal dependence, the partial derivative and total derivative is the same.

⑥ Variation in vector notation

$$\begin{aligned} \delta f &= \delta x \frac{\partial f}{\partial x} + \delta y \frac{\partial f}{\partial y} + \delta z \frac{\partial f}{\partial z} \\ &= \delta \vec{r} \cdot \vec{\nabla} f \end{aligned}$$

where

$$\begin{aligned} \delta \vec{r} &= \hat{i} \delta x + \hat{j} \delta y + \hat{k} \delta z \\ \vec{\nabla} &= \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \end{aligned}$$

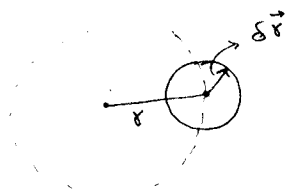
⑦ Example:

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\begin{aligned} \vec{\nabla} r &= \left[\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right] \sqrt{x^2 + y^2 + z^2} \\ &= \frac{\hat{i} x + \hat{j} y + \hat{k} z}{\sqrt{x^2 + y^2 + z^2}} \\ &= \frac{\vec{r}}{r} = \hat{r} \end{aligned}$$

⑧ Interpretation

- (i) $\vec{\nabla} f$ is normal to the curve/surface,
 $f = \text{const}$, in 2-D/3-D.



$$\begin{aligned}\delta f &= \delta \vec{r} \cdot \vec{\nabla} f \\ &= |\delta \vec{r}| |\vec{\nabla} f| \cos \theta\end{aligned}$$

- (ii) $\vec{\nabla} f$ points in the direction of maximum δf .
- (iii) Magnitude of $\vec{\nabla} f$ is the "slope" in the direction of maximum δf .
- of $\delta \vec{r}$ that leads to maximum δf .

⑨ Examples

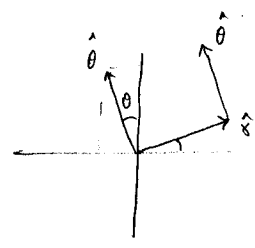
(i) $r = \sqrt{x^2 + y^2}$ is the surface of a cylinder.

$\vec{\nabla} r = \hat{r}$ is normal to the cylinder.

(ii) $\theta = \tan^{-1} \frac{y}{x}$ is the surface of a half-plane.

$$\begin{aligned}\vec{\nabla} \theta &= \hat{i} \frac{\partial}{\partial x} \tan^{-1} \frac{y}{x} + \hat{j} \frac{\partial}{\partial y} \tan^{-1} \frac{y}{x} + 0 \hat{k} \\ &= -\frac{1}{x} \sin \theta \hat{i} + \frac{1}{x} \cos \theta \hat{j}\end{aligned}$$

$$\begin{aligned}\theta &= \tan^{-1} \frac{y}{x} \\ \tan \theta &= \frac{y}{x} \\ \sec^2 \theta \frac{\partial \theta}{\partial x} &= -\frac{y}{x^2}\end{aligned}$$



$$\hat{r} = \cos \theta \hat{i} + \sin \theta \hat{j}$$

$$\hat{\theta} = \frac{\vec{\nabla} \theta}{|\vec{\nabla} \theta|} = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

⑩ Any system tends to minimize its energy. This dictates the definition of force.

$$\vec{F} = -\vec{\nabla} U$$

⑪ Examples

(i) Potential energy on surface of Earth

$$U(x, y, z) = mgz$$

$$\begin{aligned}\vec{F} &= -\vec{\nabla} U \\ &= -\hat{z} mg\end{aligned}$$

(ii) Gravitational potential energy

$$U(x, y, z) = -\frac{1}{r}$$

$$\vec{F} = -\frac{\hat{r}}{r^2}$$

$$U = -\frac{G m_1 m_2}{r}$$



(iii) Electrostatic potential energy

$$U(x, y, z) = \frac{1}{r}$$

$$\vec{F} = \frac{\hat{r}}{r^2}$$

$$U = \frac{k q_1 q_2}{r}$$