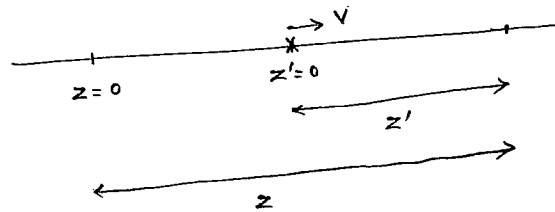


① Lorentz transformation (for boost along z-direction) is

$$\begin{pmatrix} z' \\ ct' \end{pmatrix} = \begin{pmatrix} \gamma & -\beta\gamma \\ -\beta\gamma & \gamma \end{pmatrix} \begin{pmatrix} z \\ ct \end{pmatrix}$$

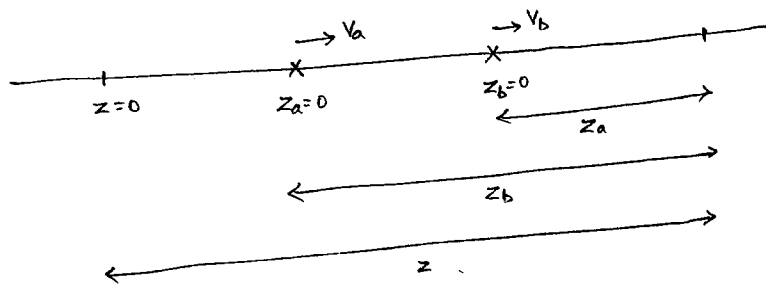
$$x' = x$$

$$y' = y$$



$$z' = z - vt$$

② Velocity addition



$$\begin{pmatrix} z_a \\ ct_a \end{pmatrix} = \begin{pmatrix} \gamma_a & -\beta_a \gamma_a \\ -\beta_a \gamma_a & \gamma_a \end{pmatrix} \begin{pmatrix} z \\ ct \end{pmatrix}$$

$$\begin{pmatrix} z_b \\ ct_b \end{pmatrix} = \begin{pmatrix} \gamma_b & -\beta_b \gamma_b \\ -\beta_b \gamma_b & \gamma_b \end{pmatrix} \begin{pmatrix} z \\ ct \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} z_a \\ ct_a \end{pmatrix} = \begin{pmatrix} \gamma_a & -\beta_a \gamma_a \\ -\beta_a \gamma_a & \gamma_a \end{pmatrix} \begin{pmatrix} \gamma_b & -\beta_b \gamma_b \\ -\beta_b \gamma_b & \gamma_b \end{pmatrix} \begin{pmatrix} z_b \\ ct_b \end{pmatrix}$$

$$= \begin{pmatrix} \gamma_a \gamma_b (1 + \beta_a \beta_b) & -(\beta_a + \beta_b) \gamma_a \gamma_b \\ -(\beta_a + \beta_b) \gamma_a \gamma_b & \gamma_a \gamma_b (1 + \beta_a \beta_b) \end{pmatrix} \begin{pmatrix} z_b \\ ct_b \end{pmatrix}$$

③ Comparing with

$$\begin{pmatrix} z_a \\ ct_a \end{pmatrix} = \begin{pmatrix} r & -\beta r \\ -\beta r & r \end{pmatrix} \begin{pmatrix} z_b \\ ct_b \end{pmatrix}$$

we learn

$$\beta r = (\beta_a + \beta_b) r_a r_b \quad \text{--- (i)}$$

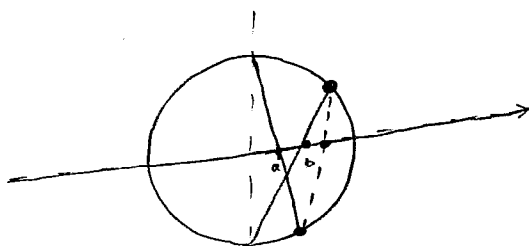
$$r = (1 + \beta_a \beta_b) r_a r_b \quad \text{--- (ii)}$$

which when divided leads to the velocity addition formula

$$\beta = \frac{v}{c}, \quad \beta_a = \frac{v_a}{c}, \quad \beta_b = \frac{v_b}{c}$$

$$\beta = \frac{\beta_a + \beta_b}{1 + \beta_a \beta_b}$$

④ Jerzy Kocik's geometric diagram for velocity addition:



→ Presuming velocity addition holds for subluminal and superluminal this diagram helps in analysis.

⑤ Lorentz transformation leaves the following "distance" invariant

$$\begin{aligned} -\Delta s^2 &= -c^2 \Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2 \\ &= -c^2 \Delta t'^2 + \Delta x'^2 + \Delta y'^2 + \Delta z'^2 \end{aligned}$$

For infinitely small displacements we have

$$-ds^2 = c^2 dt^2 + dx^2 + dy^2 + dz^2$$

⑥ We make the observation that

$$-ds^2 = \begin{pmatrix} -cdt & dx & dy & dz \end{pmatrix} \begin{pmatrix} cdt \\ dx \\ dy \\ dz \end{pmatrix}$$

⑦ We define the components of a contravariant and covariant vector as

$$\begin{aligned} x^\mu &= (x^0, x^1, x^2, x^3) \equiv (ct, \vec{x}) \rightarrow \text{contravariant vector} \\ x_\mu &= (x_0, x_1, x_2, x_3) \equiv (-ct, \vec{x}) \rightarrow \text{covariant vector} \end{aligned}$$

⑧ Greek indices: $\mu, \nu, \alpha, \beta: 0, 1, 2, 3$
 Latin indices: $i, j, m, n: 1, 2, 3$

⑨ We introduce the metric tensor, whose components are,

$$g_{\mu\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad g^{\mu\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \delta^\mu_\nu = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

such that

$$g^{\mu\lambda} g_{\lambda\nu} = \delta^\mu_\nu.$$

⑩ The metric tensor transform a contravariant vector into a covariant vector or vice versa.

$$x_\mu = g_{\mu\nu} x^\nu$$

$$x^\mu = g^{\mu\nu} x_\nu$$

⑪ Thus,

$$\begin{aligned} x_0 &= g_{0\nu} x^\nu = g_{00} x^0 + g_{01} x^1 + g_{02} x^2 + g_{03} x^3 \\ &= g_{00} x^0 = -x^0 \end{aligned}$$

$$x_1 = g_{1\nu} x^\nu = g_{11} x^1 = x^1$$

$$x_2 = g_{2\nu} x^\nu = g_{22} x^2 = x^2$$

$$x_3 = g_{3\nu} x^\nu = g_{33} x^3 = x^3$$