

# Solutions

## Prob. 1

$$x(t) = 24t^2 - 3.0t^4$$

$$v(t) = \frac{dx}{dt} = 48t - 12t^3$$

$$\begin{aligned} \text{stops} \Rightarrow v(t) = 0 &\Rightarrow 48t - 12t^3 = 0 \\ &\Rightarrow t(4 - t^2) = 0 \\ &\Rightarrow t = 0, \pm 2 \text{ s} \end{aligned}$$

Thus it stops at  $t = 2.0 \text{ s}$ .

$$a(t) = \frac{dv}{dt} = 48 - 36t^2$$

$$a(2) = 48 - 36(2)^2 = -96 \frac{\text{m}}{\text{s}^2}$$

## Prob. 2

$$\Delta x =$$

$$v_{ix} = 3.50 \frac{\text{m}}{\text{s}}$$

$$\Delta t =$$

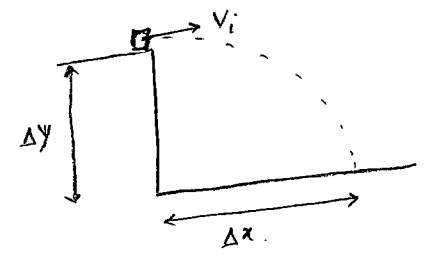
$$\Delta y = -1.30 \text{ m}$$

$$\Delta t =$$

$$v_{iy} = 0$$

$$v_{iy} =$$

$$a_y = -9.8 \frac{\text{m}}{\text{s}^2}$$



$$\begin{aligned} \Delta y &= v_{iy} \Delta t + \frac{1}{2} a_y \Delta t^2 \\ -1.30 &= \frac{1}{2} (-9.8) \Delta t^2 \\ \Delta t &= 0.515 \text{ s} \end{aligned}$$
$$\begin{aligned} \Delta x &= v_{ix} \Delta t \\ &= 3.50 \times 0.515 \\ &= 1.80 \text{ m} \end{aligned}$$

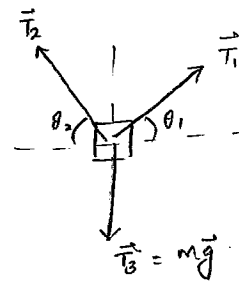
Prob. 3

$$\vec{T}_1 + \vec{T}_2 + \vec{T}_3 = m\vec{a} = 0$$

$$\overset{x}{T_1 \cos \theta_1} - T_2 \cos \theta_2 = 0$$

$$T_1 \sin \theta_1 + T_2 \sin \theta_2 = mg$$

$$\overset{y}{T_1 \sin \theta_1 + T_2 \sin \theta_2 - mg = 0}$$



$$T_1 = \frac{mg \cos \theta_1}{\cos \theta_1 \sin \theta_2 + \sin \theta_1 \cos \theta_2} = \frac{mg \cos \theta_1}{\sin(\theta_1 + \theta_2)} = \frac{450 \cos 20}{\sin(20+70)} = 423 \text{ N}$$

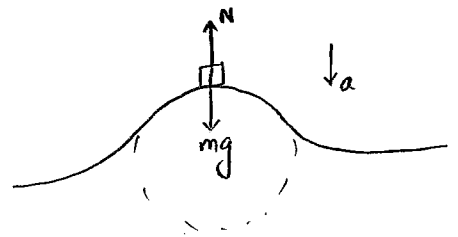
$$T_2 = \frac{mg \cos \theta_2}{\sin(\theta_1 + \theta_2)} = \frac{450 \cos 70}{\sin(20+70)} = 154 \text{ N}$$

Prob. 4

$$-mg + N = -\frac{mv^2}{R}$$

threshold is decided by  $N=0$ .

$$N=0 \Rightarrow mg = \frac{mv_{\max}^2}{R}$$
$$v_{\max} = \sqrt{gR} = \sqrt{9.8 \times 325} = 56.4 \frac{m}{s}$$



Prob. 5

(a) Normal force is always perpendicular to direction of motion. Thus, work done by normal force is zero.

$$(b) W_g = -mg \Delta h$$
$$= -4.50 \times 9.8 \times (4.0 - 7.0)$$
$$= 132.3 \text{ J}$$

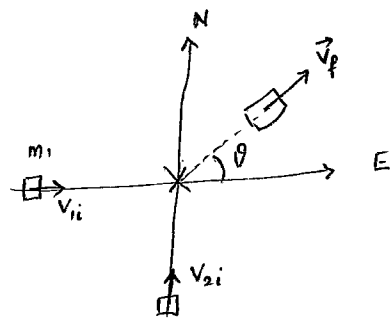
Prob. 6

$$m_1 \vec{V}_{1i} + m_2 \vec{V}_{2i} = (m_1 + m_2) \vec{V}_f$$

$$\vec{V}_f = \left( \frac{m_1}{m_1 + m_2} \right) \vec{V}_{1i} + \left( \frac{m_2}{m_1 + m_2} \right) \vec{V}_{2i}$$

$$= \frac{1}{4} \times 10.0 \hat{i} + \frac{3}{4} \times 20.0 \hat{j}$$

$$= (2.50 \hat{i} + 15.0 \hat{j}) \frac{m}{s}$$



magnitude:  $|\vec{V}_f| = \sqrt{2.50^2 + 15.0^2} = 15.2 \frac{m}{s}$

direction:  $\theta = \tan^{-1} \left( \frac{V_{fy}}{V_{fx}} \right) = \tan^{-1} \left( \frac{15.0}{2.50} \right) = 80.5^\circ$  North of East

Prob. 7

Newton's law (linear)

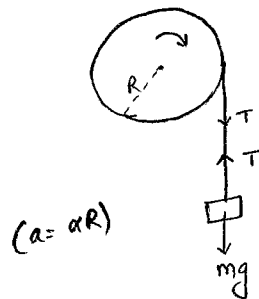
$$mg - T = ma$$

Newton's law (rotation)

$$TR = I \alpha$$

$$T = \frac{1}{2} MR^2 \frac{\alpha}{R}$$

$$= \frac{1}{2} M a$$



$$mg - \left( \frac{1}{2} M a \right) = ma$$

$$mg = \left( m + \frac{M}{2} \right) a$$

$$a = \frac{m}{\left( m + \frac{M}{2} \right)} g = \frac{5.0}{\left( 5.0 + \frac{3.00}{2} \right)} \times 9.8 = 7.54 \frac{m}{s^2}$$

Prob. 8

$$I_{disc} \omega_i + I_{student} \omega_i = I_{disc} \omega_f + I_{student} \omega_f$$

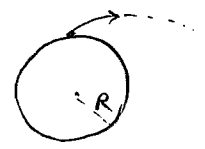
$$\begin{aligned} \omega_f &= \omega_i \left( 1 + \frac{I_{student}}{I_{disc}} \right) \\ &= \omega_i \left( 1 + \frac{m R^2}{I_{disc}} \right) \\ &= 2.4 \frac{\text{rad}}{\text{s}} \left( 1 + \frac{150 \text{ kg} (2.0 \text{ m})^2}{300 \text{ kg m}^2} \right) = 7.2 \frac{\text{rad}}{\text{s}} \end{aligned}$$

Prob. 9

$$K_i + U_i = K_f + U_f$$

$$\frac{1}{2} m v^2 - \frac{GMm}{R} = 0 + 0$$

$$\begin{aligned} v &= \sqrt{\frac{2GM}{R}} = \sqrt{\frac{2 \times 6.67 \times 10^{-11} \times 1.898 \times 10^{27} \text{ kg}}{69.9 \times 10^6 \text{ m}}} \\ &= 60.2 \frac{\text{km}}{\text{s}} \end{aligned}$$



Prob. 10

$$\vec{F}_{41} = \hat{i} \frac{Gm^2}{L^2} + \hat{j} 0$$

$$\vec{F}_{42} = \hat{i} \frac{Gm^2}{(\sqrt{2}L)^2} \cos 45^\circ + \hat{j} \frac{Gm^2}{(\sqrt{2}L)^2} \sin 45^\circ$$

$$\vec{F}_{43} = \hat{i} 0 + \hat{j} \frac{Gm^2}{L^2}$$

$$\vec{F}_{tot} = \frac{Gm^2}{L^2} \left( 1 + \frac{1}{2\sqrt{2}} \right) \hat{i} + \frac{Gm^2}{L^2} \left( 1 + \frac{1}{2\sqrt{2}} \right) \hat{j}$$

magnitude:  $|\vec{F}_{tot}| = \frac{Gm^2}{L^2} \left( \sqrt{2} + \frac{1}{2} \right)$

direction:  $45^\circ$  counter clockwise w.r.t. one axis.

