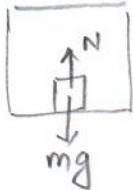


Problem 1

$$\downarrow a=g$$

$$-ma = -mg + N$$

$$\begin{aligned} N &= mg - ma \\ &= mg - mg \\ &= 0 \end{aligned}$$

Scale reads 0.

Problem 2

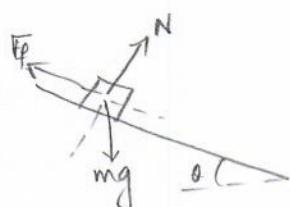
The accelerations will be identical. The tension in the ropes are the same at the ends because of the assumption that they are massless.

Problem 3

No, they are not. Action and reaction forces never act on the same mass.

Problem 4

Since the mass is at rest we have



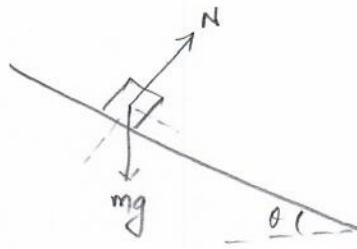
$$\begin{aligned} F_f &= mg \sin \theta \\ &= (10.0)(9.8) \sin 30 \\ &= 49 \text{ Newtons} \end{aligned}$$

Problem 5

$$\begin{aligned}
 g_{\text{planet}} &= \frac{G M_p}{R_p^2} & M_p = 100 M_E \\
 &= \frac{G 100 M_E}{(10 R_E)^2} & R_p = 10 R_E \\
 &= \frac{G M_E}{R_E^2} = g = 9.8 \frac{m}{s^2}
 \end{aligned}$$

Problem 6

$$\begin{aligned}
 m \vec{a} &= m \vec{g} + \vec{N} \\
 m a &= mg \sin \theta & N = mg \cos \theta \\
 a &= g \sin \theta & = (75)(9.8) \cos 30 \\
 &= (9.8) \sin 30 & = 637 \text{ Newtons} \\
 &= 4.9 \frac{m}{s^2}
 \end{aligned}$$



$$(a) N = mg \cos \theta = 637 \text{ Newtons}$$

$$(b) a = g \sin \theta = 4.9 \frac{m}{s^2}$$

$$(c) \Delta x = 6.0 \text{ m}$$

$$\Delta t = ?$$

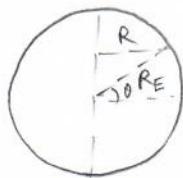
$$v_i = 0 \quad a = 4.9 \frac{m}{s^2}$$

$$\begin{aligned}
 \Delta x &= v_i \Delta t + \frac{1}{2} a \Delta t^2 \\
 6.0 &= 0 + \frac{1}{2} 4.9 \Delta t^2
 \end{aligned}$$

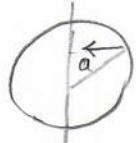
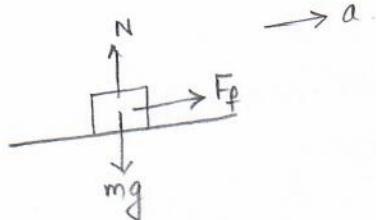
$$\Delta t = 1.6 \frac{m}{s^2}$$

Problem 7

$$\begin{aligned}
 a_c &= \omega^2 R = \omega^2 R_E \cos\theta \\
 &= \frac{4\pi^2}{T^2} R_E \cos\theta \\
 &= \frac{4\pi^2 (6.4 \times 10^6)}{(24 \times 60 \times 60)^2} \cos 30 \\
 &= 0.034 \cos 30 = 0.029 \frac{\text{m}}{\text{s}^2}.
 \end{aligned}$$



direction: towards the axis.

Problem 8

$$m\vec{a} = m\vec{g} + \vec{N} + \vec{F}_f$$

$$\underline{x\text{-dir}} \\ ma = F_f$$

$$\underline{y\text{-dir}} \\ N = mg$$

$$F_f \leq \mu_s N$$

$$ma \leq \mu_s mg$$

$$a \leq \mu_s g = (0.5)(9.8) = 4.9 \frac{\text{m}}{\text{s}^2}$$

maximum acceleration is $4.9 \frac{\text{m}}{\text{s}^2}$.