# Homework No. 08 (2025 Spring)

#### PHYS 510: CLASSICAL MECHANICS

School of Physics and Applied Physics, Southern Illinois University-Carbondale

Due date: Thursday, 2025 Mar 20, 4.30pm

- 1. (20 points.) (Refer Landau and Lifshitz, Problem 1 in Chapter 3.) A simple pendulum consists of a particle of mass m suspended by a massless rod of length l in a uniform gravitational field g.
  - (a) Identify the two forces acting on the pendulum to be the force of gravity  $m\mathbf{g}$  and the force of tension  $\mathbf{T}$ . Thus, deduce the Newton equation of motion to be

$$m\mathbf{a} = m\mathbf{g} + \mathbf{T},\tag{1}$$

where **a** is acceleration of mass m. Starting from Eq. (1) derive the equation of motion for the simple pendulum

$$\frac{d^2\phi}{dt^2} = -\omega_0^2 \sin\phi,\tag{2}$$

where

$$\omega_0 = \frac{2\pi}{T_0} = \sqrt{\frac{g}{l}}. (3)$$

(b) Starting from Eq. (2) derive the statement of conservation of energy for this system,

$$\frac{1}{2}ml^2\dot{\phi}^2 - mgl\cos\phi = \text{constant.} \tag{4}$$

Hint: Multiply Eq. (2) by  $\phi$  and express the equation as a total derivative with respect to time.

(c) For initial conditions  $\phi(0) = \phi_0$  and  $\dot{\phi}(0) = 0$  show that

$$\frac{1}{2}ml^2\dot{\phi}^2 - mgl\cos\phi = -mgl\cos\phi_0. \tag{5}$$

Thus, derive

$$\frac{dt}{T_0} = \frac{1}{2\pi} \frac{d\phi}{\sqrt{2(\cos\phi - \cos\phi_0)}}\tag{6}$$

where  $T_0 = 2\pi \sqrt{l/g}$ .

(d) The time period of oscillations of the simple pendulum is equal to four times the time taken between  $\phi = 0$  and  $\phi = \phi_0$ . Thus, show that

$$T = 4\frac{T_0}{2\pi} \int_0^{\phi_0} \frac{d\phi}{\sqrt{2(\cos\phi - \cos\phi_0)}}$$
 (7)

$$= \frac{T_0}{\pi} \int_0^{\phi_0} \frac{d\phi}{\sqrt{\sin^2 \frac{\phi_0}{2} - \sin^2 \frac{\phi}{2}}}.$$
 (8)

Then, substitute  $\sin \theta = \sin(\phi/2)/\sin(\phi_0/2)$  to determine the period of oscillations of the simple pendulum as a function of the amplitude of oscillations  $\phi_0$  to be

$$T = T_0 \frac{2}{\pi} K \left( \sin \frac{\phi_0}{2} \right), \tag{9}$$

where

$$K(k) = \int_0^{\frac{\pi}{2}} \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}} \tag{10}$$

is the complete elliptic integral of the first kind.

(e) Using the power series expansion

$$K(k) = \frac{\pi}{2} \sum_{n=0}^{\infty} \left[ \frac{(2n)!}{2^{2n} (n!)^2} \right]^2 k^{2n}$$
 (11)

show that for small oscillations  $(\phi_0/2 \ll 1)$ 

$$T = T_0 \left[ 1 + \frac{\phi_0^2}{16} + \dots \right]. \tag{12}$$

- (f) Estimate the percentage error made in the approximation  $T \sim T_0$  for  $\phi_0 \sim 60^\circ$ .
- (g) Plot the time period T of Eq. (9) as a function of  $\phi_0$ . What can you conclude about the time period for  $\phi_0 = \pi$ ?
- 2. (20 points.) Consider the differential equation

$$\ddot{x}(t) = -\omega_1^2 x(t),\tag{13}$$

where dot denotes differentiation with respect to time, in conjunction with a suitable initial condition.

(a) Using Fourier transform

$$x(t) = \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{-i\omega t} \tilde{x}(\omega), \qquad (14a)$$

$$\tilde{x}(\omega) = \int_{-\infty}^{\infty} dt \, e^{i\omega t} x(t),\tag{14b}$$

show that  $\tilde{x}(\omega)$  satisfies the algebraic equation

$$-\omega^2 \tilde{x}(\omega) = -\omega_1^2 \tilde{x}(\omega). \tag{15}$$

Observe that we can arrive at this equation using the transcription,

$$\frac{\partial}{\partial t} \to -i\omega,$$
 (16a)

$$x(t) \to \tilde{x}(\omega),$$
 (16b)

in the original differential equation. Thus, the algebraic equation for  $\tilde{x}(\omega)$  is

$$(\omega^2 - \omega_1^2)\tilde{x}(\omega) = 0. \tag{17}$$

(b) The solution to the above algebraic equation can be expressed in the form

$$\tilde{x}(\omega) = \tilde{\alpha}(\omega)\delta(\omega^2 - \omega_1^2),\tag{18}$$

where  $\tilde{\alpha}(\omega)$  is to be determined. Using the property of  $\delta$ -functions show that

$$\tilde{x}(\omega) = \frac{\tilde{\alpha}(\omega_1)}{2\omega_1}\delta(\omega - \omega_1) + \frac{\tilde{\alpha}(-\omega_1)}{2\omega_1}\delta(\omega + \omega_1). \tag{19}$$

### (c) Using Fourier transform evaluate

$$x(t) = \frac{1}{2\pi} \frac{\tilde{\alpha}(\omega_1)}{2\omega_1} e^{-i\omega_1 t} + \frac{1}{2\pi} \frac{\tilde{\alpha}(-\omega_1)}{2\omega_1} e^{i\omega_1 t}.$$
 (20)

In terms of numbers

$$A_1 = \frac{1}{2\pi} \frac{\tilde{\alpha}(\omega_1)}{2\omega_1},\tag{21a}$$

$$B_1 = \frac{1}{2\pi} \frac{\tilde{\alpha}(-\omega_1)}{2\omega_1},\tag{21b}$$

express the solution in the form

$$x(t) = A_1 e^{-i\omega_1 t} + B_1 e^{i\omega_1 t}. (22)$$

The numbers  $A_1$  and  $B_1$  are determined from initial conditions. For example, show that for initial conditions x(0) = A and  $\dot{x}(0) = 0$  the solution is

$$x(t) = A\cos\omega_1 t. \tag{23}$$

## 3. (20 points.) Consider the set of differential equations

$$\ddot{x}_1(t) + \omega_1^2 x_1(t) = \omega_3^2 x_2(t), \tag{24a}$$

$$\ddot{x}_2(t) + \omega_2^2 x_2(t) = \omega_3^2 x_1(t), \tag{24b}$$

where dot denotes differentiation with respect to time, in conjunction with suitable initial conditions.

(a) Using Fourier transform show that  $\tilde{x}_1(\omega)$  and  $\tilde{x}_2(\omega)$  satisfy the algebraic equations

$$(\omega_1^2 - \omega^2)\tilde{x}_1(\omega) - \omega_3^2 \tilde{x}_2(\omega) = 0, \tag{25a}$$

$$-\omega_3^2 \tilde{x}_1(\omega) + (\omega_2^2 - \omega^2) \tilde{x}_2(\omega) = 0.$$
 (25b)

Observe that they decouple for  $\omega_3 = 0$ . The explicit nature of the coupling is brought out by writing the solutions,  $\tilde{x}_1(\omega)$  and  $\tilde{x}_2(\omega)$ , in the form

$$\tilde{x}_1(\omega) = \frac{\omega_3^2}{(\omega_1^2 - \omega^2)} \tilde{x}_2(\omega), \tag{26a}$$

$$\tilde{x}_2(\omega) = \frac{\omega_3^2}{(\omega_2^2 - \omega^2)} \tilde{x}_1(\omega). \tag{26b}$$

Using the two solutions in conjunction show that the solutions satisfy

$$(\omega - \lambda_1)(\omega + \lambda_1)(\omega - \lambda_2)(\omega + \lambda_2)\tilde{x}_1(\omega) = 0, \tag{27a}$$

$$(\omega - \lambda_1)(\omega + \lambda_1)(\omega - \lambda_2)(\omega + \lambda_2)\tilde{x}_2(\omega) = 0, \tag{27b}$$

where  $\pm \lambda_1$  and  $\pm \lambda_2$  are roots of the quartic equation

$$(\omega^2 - \omega_1^2)(\omega^2 - \omega_2^2) - \omega_3^4 = 0. \tag{28}$$

Evaluate the roots for  $\omega_2^2 > \omega_1^2$  to be

$$\lambda_2^2 = \frac{(\omega_2^2 + \omega_1^2)}{2} + \frac{1}{2}\sqrt{(\omega_2^2 - \omega_1^2)^2 + 4\omega_3^4},\tag{29a}$$

$$\lambda_1^2 = \frac{(\omega_2^2 + \omega_1^2)}{2} - \frac{1}{2}\sqrt{(\omega_2^2 - \omega_1^2)^2 + 4\omega_3^4},\tag{29b}$$

and express them in the form

$$\lambda_2^2 = \omega_2^2 + (\mu^2 - \Delta^2),\tag{30a}$$

$$\lambda_1^2 = \omega_1^2 - (\mu^2 - \Delta^2),\tag{30b}$$

where

$$\Delta^2 = \frac{(\omega_2^2 - \omega_1^2)}{2} \tag{31}$$

and

$$\mu^2 = \sqrt{\Delta^4 + \omega_3^4}. (32)$$

Determine the normal modes  $\lambda_1$  and  $\lambda_2$  for  $\omega_3 = 0$ .

(b) Derive the following. The difference in the square of roots,

$$\lambda_2^2 - \lambda_1^2 = 2\mu^2, (33)$$

and the change in the normal modes due to coupling,

$$\omega_1^2 - \lambda_1^2 = (\mu^2 - \Delta^2), \tag{34a}$$

$$\omega_1^2 - \lambda_2^2 = -(\mu^2 + \Delta^2), \tag{34b}$$

and

$$\omega_2^2 - \lambda_1^2 = (\mu^2 + \Delta^2), \tag{35a}$$

$$\omega_2^2 - \lambda_2^2 = -(\mu^2 - \Delta^2). \tag{35b}$$

Using the above relations together with

$$\omega_3^2 = \sqrt{(\mu^2 + \Delta^2)(\mu^2 - \Delta^2)} \tag{36}$$

derive

$$\frac{\omega_3^2}{(\omega_1^2 - \lambda_1^2)} = \sqrt{\frac{\mu^2 + \Delta^2}{\mu^2 - \Delta^2}} = -\frac{\omega_3^2}{(\omega_2^2 - \lambda_2^2)},\tag{37a}$$

$$\frac{\omega_3^2}{(\omega_2^2 - \lambda_1^2)} = \sqrt{\frac{\mu^2 - \Delta^2}{\mu^2 + \Delta^2}} = -\frac{\omega_3^2}{(\omega_1^2 - \lambda_2^2)}.$$
 (37b)

(c) Argue that the solutions for the algebraic expressions in Eqs. (27) can be expressed in the form

$$\tilde{x}_1(\omega) = \tilde{a}_1(\omega)\delta((\omega - \lambda_1)(\omega + \lambda_1)(\omega - \lambda_2)(\omega + \lambda_2)), \tag{38a}$$

$$\tilde{x}_2(\omega) = \tilde{a}_2(\omega)\delta((\omega - \lambda_1)(\omega + \lambda_1)(\omega - \lambda_2)(\omega + \lambda_2)), \tag{38b}$$

where  $\tilde{a}_1(\omega)$  and  $\tilde{a}_2(\omega)$  are arbitrary. Using the property of  $\delta$ -functions show that

$$\frac{\tilde{x}_1(\omega)}{2\pi} = \frac{1}{8\pi\mu^2} \left[ \frac{\tilde{a}_1(\lambda_1)}{\lambda_1} \delta(\omega - \lambda_1) + \frac{\tilde{a}_1(-\lambda_1)}{\lambda_1} \delta(\omega + \lambda_1) + \frac{\tilde{a}_1(\lambda_2)}{\lambda_2} \delta(\omega - \lambda_2) + \frac{\tilde{a}_1(-\lambda_2)}{\lambda_2} \delta(\omega + \lambda_2) \right],$$
(39a)

$$\frac{\tilde{x}_2(\omega)}{2\pi} = \frac{1}{8\pi\mu^2} \left[ \frac{\tilde{a}_2(\lambda_1)}{\lambda_1} \delta(\omega - \lambda_1) + \frac{\tilde{a}_2(-\lambda_1)}{\lambda_1} \delta(\omega + \lambda_1) + \frac{\tilde{a}_2(\lambda_2)}{\lambda_2} \delta(\omega - \lambda_2) + \frac{\tilde{a}_2(-\lambda_2)}{\lambda_2} \delta(\omega + \lambda_2) \right].$$
(39b)

The aribitrary coefficients are related due to the coupling in Eqs. (26). Thus, verify that

$$\tilde{a}_1(\pm \lambda_1) = \sqrt{\frac{\mu^2 + \Delta^2}{\mu^2 - \Delta^2}} \tilde{a}_2(\pm \lambda_1),$$
(40a)

$$\tilde{a}_1(\pm \lambda_2) = -\sqrt{\frac{\mu^2 - \Delta^2}{\mu^2 + \Delta^2}} \tilde{a}_2(\pm \lambda_2), \tag{40b}$$

and

$$\tilde{a}_2(\pm\lambda_1) = \sqrt{\frac{\mu^2 - \Delta^2}{\mu^2 + \Delta^2}} \tilde{a}_1(\pm\lambda_1), \tag{41a}$$

$$\tilde{a}_2(\pm \lambda_2) = -\sqrt{\frac{\mu^2 + \Delta^2}{\mu^2 - \Delta^2}} \tilde{a}_1(\pm \lambda_2). \tag{41b}$$

Using Eqs. (39) in the Fourier transform

$$x(t) = \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} e^{-i\omega t} \tilde{x}_1(\omega)$$
 (42)

and the redefinitions

$$A_1 = \frac{1}{8\pi\mu^2} \frac{\tilde{a}_1(\lambda_1)}{\lambda_1} \qquad B_1 = \frac{1}{8\pi\mu^2} \frac{\tilde{a}_1(-\lambda_1)}{\lambda_1}, \tag{43a}$$

$$A_2 = \frac{1}{8\pi\mu^2} \frac{\tilde{a}_1(\lambda_2)}{\lambda_2} \qquad B_2 = \frac{1}{8\pi\mu^2} \frac{\tilde{a}_1(-\lambda_2)}{\lambda_2}, \tag{43b}$$

which are determined by initial conditions, show that

$$x_1(t) = A_1 e^{-i\lambda_1 t} + B_1 e^{i\lambda_1 t} + A_2 e^{-i\lambda_2 t} + B_2 e^{i\lambda_2 t},$$
(44a)

$$x_2(t) = \sqrt{\frac{\mu^2 - \Delta^2}{\mu^2 + \Delta^2}} \left[ A_1 e^{-i\lambda_1 t} + B_1 e^{i\lambda_1 t} \right] - \sqrt{\frac{\mu^2 + \Delta^2}{\mu^2 - \Delta^2}} \left[ A_2 e^{-i\lambda_2 t} + B_2 e^{i\lambda_2 t} \right]. \tag{44b}$$

### (d) For initial conditions

$$x_1(0) = A, \quad \dot{x}_1(0) = 0, \quad x_2(0) = 0, \quad \dot{x}_2(0) = 0,$$
 (45)

show that

$$x_1(t) = \frac{A}{2} \left[ \left( 1 + \frac{\Delta^2}{\mu^2} \right) \cos \lambda_1 t + \left( 1 - \frac{\Delta^2}{\mu^2} \right) \cos \lambda_2 t \right], \tag{46a}$$

$$x_2(t) = \frac{A}{2} \frac{\omega_3^2}{\mu^2} \left[ \cos \lambda_1 t - \cos \lambda_2 t \right]. \tag{46b}$$

Sympathetic oscillations are characterized by the case

$$\Delta^2 \ll \omega_3^2 \tag{47}$$

when

$$\left(1 \pm \frac{\Delta^2}{\mu^2}\right) \sim 1, \quad \frac{\omega_3^2}{\mu^2} \sim 1, \quad \lambda_2^2 \sim \omega_2^2 + \omega_3^2, \quad \lambda_1^2 \sim \omega_1^2 - \omega_3^2,$$
 (48)

and

$$x_1(t) = \frac{A}{2} \left[ \cos \lambda_1 t + \cos \lambda_2 t \right] = A \cos \left( \frac{\lambda_1 - \lambda_2}{2} \right) t \cos \left( \frac{\lambda_1 + \lambda_2}{2} \right) t, \tag{49a}$$

$$x_2(t) = \frac{A}{2} \left[ \cos \lambda_1 t - \cos \lambda_2 t \right] = A \sin \left( \frac{\lambda_1 - \lambda_2}{2} \right) t \cos \left( \frac{\lambda_1 + \lambda_2}{2} \right) t. \tag{49b}$$

Plot  $x_1(t)$  and  $x_2(t)$  for  $\omega_2 = 1.01\omega_1$  and  $\omega_3 = 0.3\omega_1$ , corresponding to  $\omega_3 \sim 10\Delta$ .

(e) The following 21 minute long Veritasium YouTube video discusses synchronization in a variety of systems,

https://youtu.be/t-\_VPRCtiUg.

Discuss if these examples constitute sympathetic oscillations.  $\,$